

Features

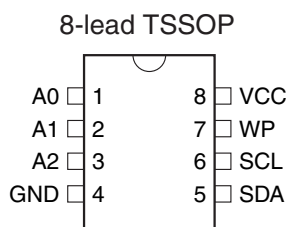
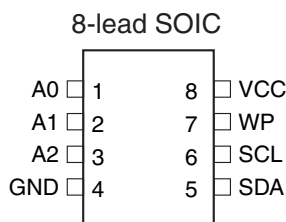
- Write Protect Pin for Hardware Data Protection
 - Utilizes Different Array Protection Compared to the AT24C02A/04A
- Standard-voltage Operation
 - 2.7 ($V_{CC} = 2.7V$ to 5.5V)
- Internally Organized 256 x 8 (2K), 512 x 8 (4K)
- Two-wire Serial Interface
- Schmitt Trigger, Filtered Inputs for Noise Suppression
- Bidirectional Data Transfer Protocol
- 400 kHz Clock Rate
- 8-byte Page (2K), 16-byte Page (4K) Write Modes
- Partial Page Writes Allowed
- Self-timed Write Cycle (5 ms Max)
- High Reliability
 - Endurance: One Million Write Cycles
 - Data Retention: 100 Years
- Lead-Free/Halogen-Free Devices Available
- 8-lead JEDEC SOIC and 8-lead TSSOP Packages

Description

The AT24C02A/04A provides 2048/4096 bits of serial electrically erasable and programmable read-only memory (EEPROM) organized as 256/512 words of 8 bits each. The device is optimized for use in many automotive applications where low-power and low-voltage operation are essential. The AT24C02A/04A is available in space-saving 8-lead JEDEC SOIC and 8-lead TSSOP packages and is accessed via a two-wire serial interface. In addition, the entire family is available in 2.7V (2.7V to 5.5V) version.

Table 1. Pin Configurations

| Pin Name | Function |
|----------|--------------------|
| A0–A2 | Address Inputs |
| SDA | Serial Data |
| SCL | Serial Clock Input |
| WP | Write Protect |
| NC | No-connect |



Two-wire Automotive Temperature Serial EEPROM

2K (256 x 8)

4K (512 x 8)

AT24C02A⁽¹⁾ AT24C04A

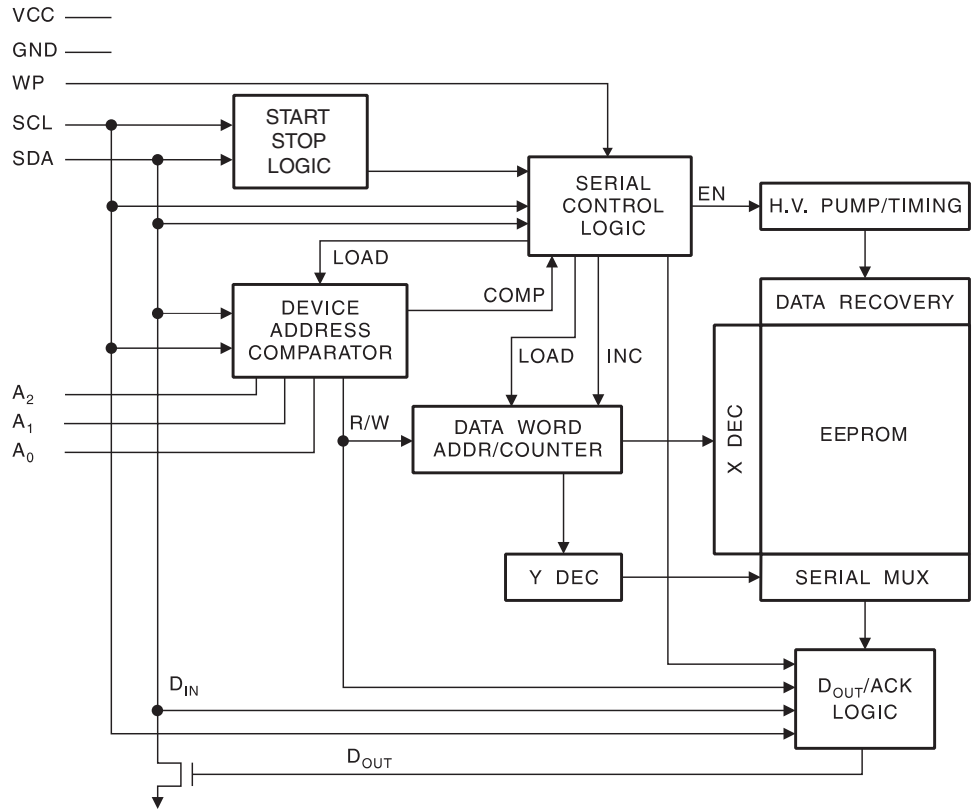
Note: 1. AT24C02A not recommended for new design; please refer to the AT24HC02B Automotive datasheet.

Absolute Maximum Ratings*

| | |
|---|-----------------|
| Operating Temperature..... | -40°C to +125°C |
| Storage Temperature | -65°C to +150°C |
| Voltage on Any Pin with Respect to Ground..... | -1.0V to +7.0V |
| Maximum Operating Voltage | 6.25V |
| DC Output Current..... | 5.0 mA |

***NOTICE:** Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Figure 1. Block Diagram



Pin Description

SERIAL CLOCK (SCL): The SCL input is used to positive edge clock data into each EEPROM device and negative edge clock data out of each device.

SERIAL DATA (SDA): The SDA pin is bidirectional for serial data transfer. This pin is open-drain driven and may be wire-ORed with any number of other open-drain or open-collector devices.

DEVICE/PAGE ADDRESSES (A2, A1, A0): The A2, A1, and A0 pins are device address inputs that must be hardwired for the AT24C02A. As many as eight 2K devices may be addressed on a single bus system. (Device addressing is discussed in detail under *Device Addressing*, page 7).

The AT24C04A uses the A2 and A1 inputs for hardwire addressing, and a total of four 4K devices may be addressed on a single bus system. The A0 pin is a no-connect.

WRITE PROTECT (WP): The AT24C02A/04A have a WP pin that provides hardware data protection. The WP pin allows normal read/write operations when connected to ground (GND). When the WP pin is connected to V_{CC} , the write protection feature is enabled and operates as shown. (See Table 1.)

Table 1. Write Protect

| WP Pin Status | Part of the Array Protected | |
|---------------|------------------------------|-----------------------|
| | 24C02A | 24C04A |
| At V_{CC} | Upper Half (1K) Array | Upper Half (2K) Array |
| At GND | Normal Read/Write Operations | |

Memory Organization **AT24C02A, 2K SERIAL EEPROM:** The 2K is internally organized with 32 pages of 8 bytes each. Random word addressing requires an 8-bit data word address.

AT24C04A, 4K SERIAL EEPROM: The 4K is internally organized with 32 pages of 16 bytes each. Random word addressing requires a 9-bit data word address.

Table 2. Pin Capacitance

Applicable over recommended operating range from $T_A = 25^\circ\text{C}$, $f = 1.0\text{ MHz}$, $V_{CC} = +2.7\text{V}$

| Symbol | Test Condition | Max | Units | Conditions |
|-----------|--|-----|-------|-----------------------|
| $C_{I/O}$ | Input/Output Capacitance (SDA) | 8 | pF | $V_{I/O} = 0\text{V}$ |
| C_{IN} | Input Capacitance (A_0, A_1, A_2, SCL) | 6 | pF | $V_{IN} = 0\text{V}$ |

Note: This parameter is characterized and is not 100% tested.

Table 3. DC Characteristics

Applicable over recommended operating range from: $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$, $V_{CC} = +2.7\text{V}$ to $+5.5\text{V}$ (unless otherwise noted)

| Symbol | Parameter | Test Condition | Min | Typ | Max | Units |
|-----------|---|--------------------------------|---------------------|------|---------------------|---------------|
| V_{CC3} | Supply Voltage | | 2.7 | | 5.5 | V |
| I_{CC} | Supply Current $V_{CC} = 5.0\text{V}$ | READ at 100 kHz | | 0.4 | 1.0 | mA |
| I_{CC} | Supply Current $V_{CC} = 5.0\text{V}$ | WRITE at 100 kHz | | 2.0 | 3.0 | mA |
| I_{SB3} | Standby Current $V_{CC} = 2.7\text{V}$ | $V_{IN} = V_{CC}$ or V_{SS} | | 1.6 | 4.0 | μA |
| I_{SB4} | Standby Current $V_{CC} = 5.0\text{V}$ | $V_{IN} = V_{CC}$ or V_{SS} | | 8.0 | 18.0 | μA |
| I_{LI} | Input Leakage Current | $V_{IN} = V_{CC}$ or V_{SS} | | 0.10 | 3.0 | μA |
| I_{LO} | Output Leakage Current | $V_{OUT} = V_{CC}$ or V_{SS} | | 0.05 | 3.0 | μA |
| V_{IL} | Input Low Level ⁽¹⁾ | | -0.6 | | $V_{CC} \times 0.3$ | V |
| V_{IH} | Input High Level ⁽¹⁾ | | $V_{CC} \times 0.7$ | | $V_{CC} + 0.5$ | V |
| V_{OL2} | Output Low Level $V_{CC} = 3.0\text{V}$ | $I_{OL} = 2.1\text{ mA}$ | | | 0.4 | V |
| V_{OL1} | Output Low Level $V_{CC} = 1.8\text{V}$ | $I_{OL} = 0.15\text{ mA}$ | | | 0.2 | V |

Note: 1. V_{IL} min and V_{IH} max are reference only and are not tested.

Table 4. AC Characteristics

Applicable over recommended operating range from $T = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$, $V_{\text{CC}} = +2.7\text{V}$ to $+5.5\text{V}$, $\text{CL} = 1$ TTL Gate and 100 pF (unless otherwise noted)

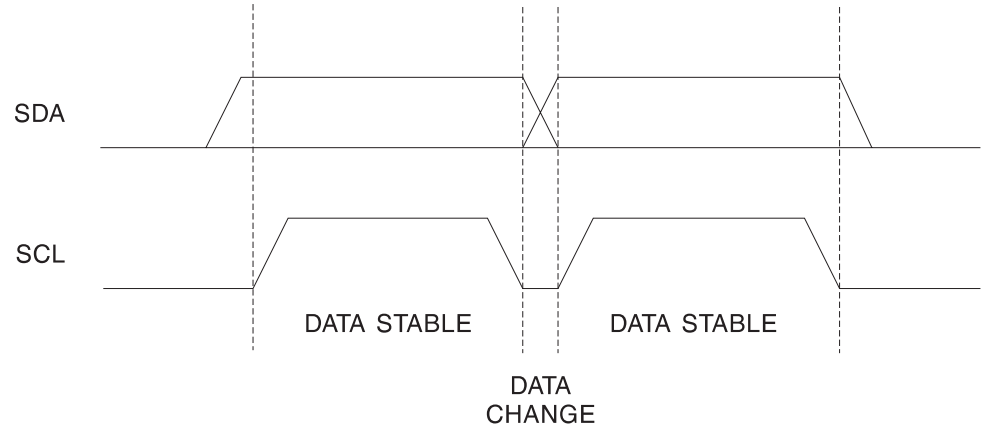
| Symbol | Parameter | AT24C02A/04A | | Units |
|--------------------------|--|--------------|-----|---------------|
| | | Min | Max | |
| f_{SCL} | Clock Frequency, SCL | | 400 | kHz |
| t_{LOW} | Clock Pulse Width Low | 1.2 | | μs |
| t_{HIGH} | Clock Pulse Width High | 0.6 | | μs |
| t_{i} | Noise Suppression Time ⁽¹⁾ | | 50 | ns |
| t_{AA} | Clock Low to Data Out Valid | 0.1 | 0.9 | μs |
| t_{BUF} | Time the bus must be free before a new transmission can start ⁽²⁾ | 1.2 | | μs |
| $t_{\text{HD,STA}}$ | Start Hold Time | 0.6 | | μs |
| $t_{\text{SU,STA}}$ | Start Set-up Time | 0.6 | | μs |
| $t_{\text{HD,DAT}}$ | Data In Hold Time | 0 | | μs |
| $t_{\text{SU,DAT}}$ | Data In Set-up Time | 100 | | ns |
| t_{R} | Inputs Rise Time ⁽²⁾ | | 300 | ns |
| t_{F} | Inputs Fall Time ⁽²⁾ | | 300 | ns |
| $t_{\text{SU,STO}}$ | Stop Set-up Time | 0.6 | | μs |
| t_{DH} | Data Out Hold Time | 50 | | ns |
| t_{WR} | Write Cycle Time | | 5 | ms |
| Endurance ⁽²⁾ | 5.0V, 25°C , Page Mode | 1M | | Write Cycles |

Note: 1. This parameter is characterized and is not 100% tested ($T_{\text{A}} = 25^{\circ}\text{C}$).
2. This parameter is characterized and is not 100% tested.

Device Operation

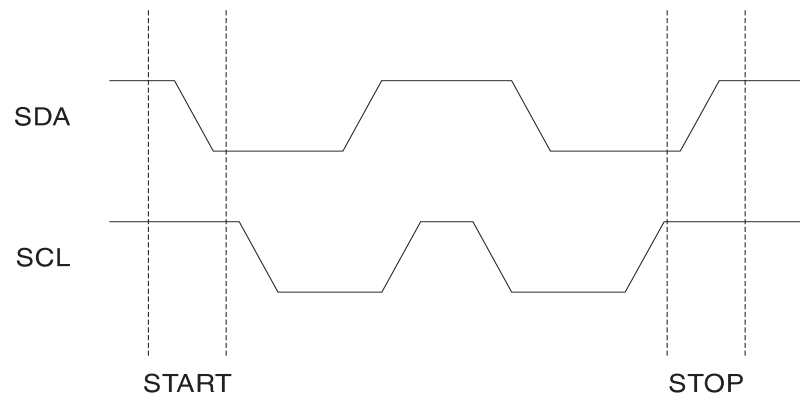
CLOCK and DATA TRANSITIONS: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see Figure 2). Data changes during SCL high periods will indicate a start or stop condition as defined in Figure 2.

Figure 2. Data Validity



START CONDITION: A high-to-low transition of SDA with SCL high is a start condition that must precede any other command (see Figure 3).

Figure 3. Start and Stop Definition



STOP CONDITION: A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the EEPROM in a standby power mode (see Figure 3).

ACKNOWLEDGE: All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The EEPROM sends a "0" to acknowledge that it has received each word. This happens during the ninth clock cycle.

STANDBY MODE: The AT24C02A/04A features a low-power standby mode that is enabled (a) upon power-up and (b) after the receipt of the STOP bit and the completion of any internal operations.

MEMORY RESET: After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps:

1. Clock up to 9 cycles.
2. Look for SDA high in each cycle while SCL is high.
3. Create a start condition as SDA is high.

Figure 4. Bus Timing

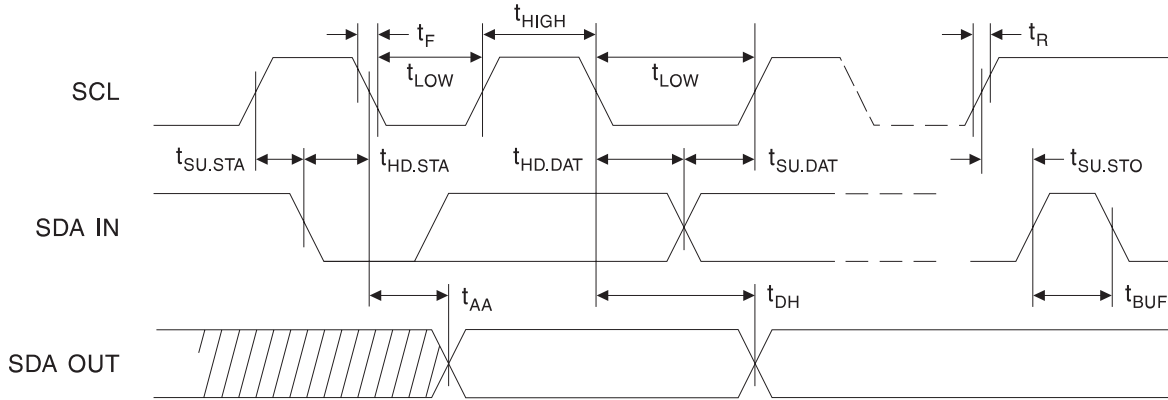
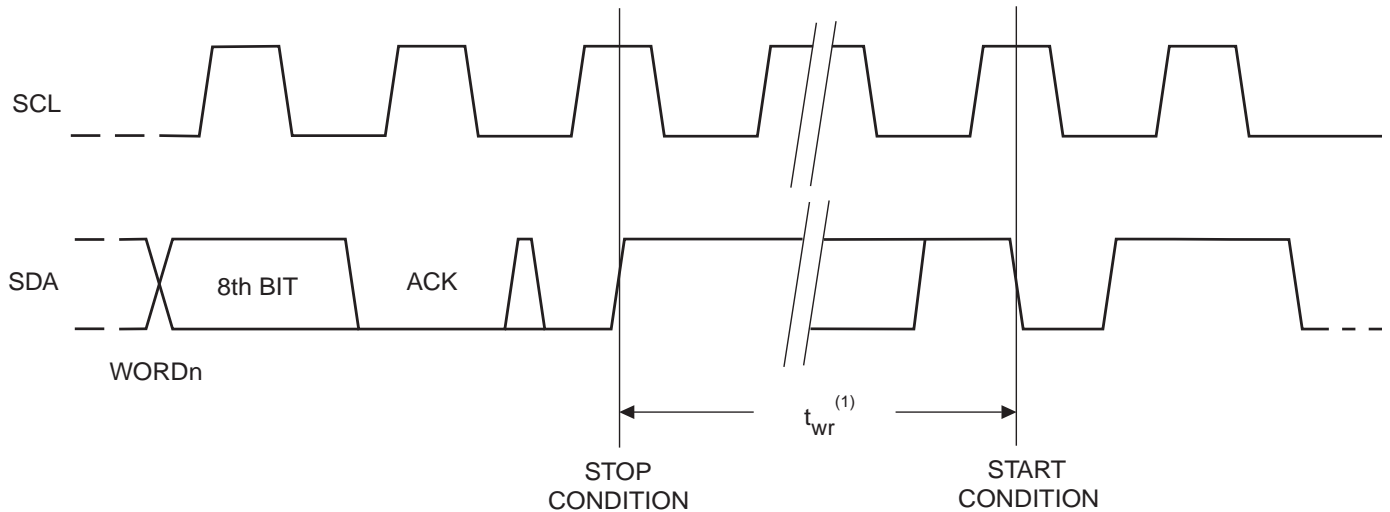
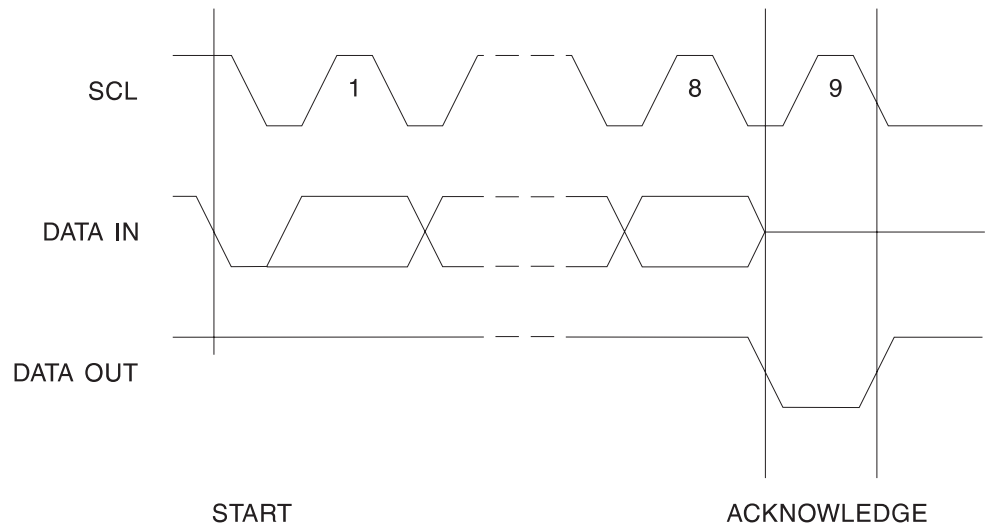


Figure 5. Write Cycle Timing



Note: The write cycle time t_{wr} is the time from a valid stop condition of a write sequence to the end of the interval clear/write cycle.

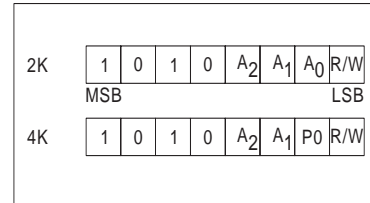
Figure 6. Output Acknowledge



Device Addressing

The 2K and 4K EEPROM devices all require an 8-bit device address word following a start condition to enable the chip for a read or write operation, as shown in Figure 7.

Figure 7. Device Address



The device address word consists of a mandatory “1”, “0” sequence for the first four most significant bits as shown. This is common to all the EEPROM devices.

The next three bits are the A₂, A₁, and A₀ device address bits for the 2K EEPROM. These three bits must compare to their corresponding hardwired input pins.

The 4K EEPROM only uses the A₂ and A₁ device address bits with the third bit being a memory page address bit. The two device address bits must compare to their corresponding hardwired input pins. The A₀ pin is no-connect.

The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high, and a write operation is initiated if this bit is low.

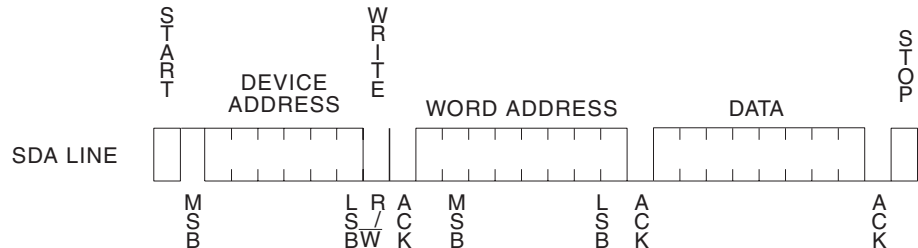
Upon a compare of the device address, the EEPROM will output a “0”. If a compare is not made, the chip will return to a standby state.

Write Operations

BYTE WRITE: A write operation requires an 8-bit data word address following the device address word and acknowledgement. Upon receipt of this address, the EEPROM will again respond with a “0” and then clock in the first 8-bit data word. Following receipt

of the 8-bit data word, the EEPROM will output a “0” and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. At this time, the EEPROM enters an internally-timed write cycle, t_{WR} , to the nonvolatile memory. All inputs are disabled during this write cycle, and the EEPROM will not respond until the write is complete, as shown in Figure 8.

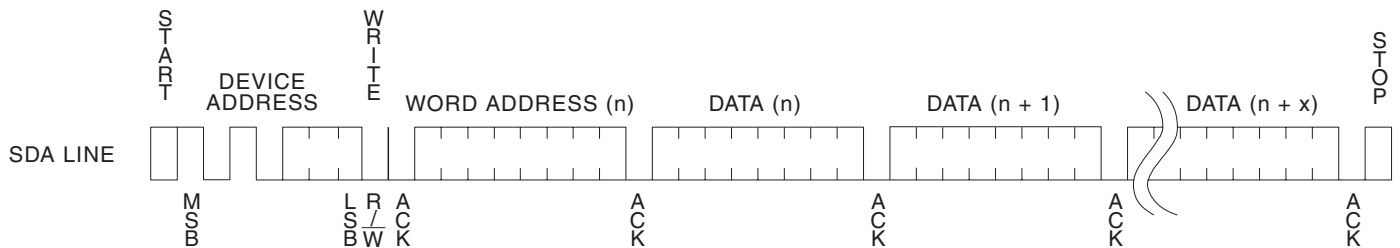
Figure 8. Byte Write



PAGE WRITE: The 2K EEPROM is capable of an 8-byte page write, and the 4K EEPROM device is capable of 16-byte page writes.

A page write is initiated the same as a byte write, but the microcontroller does not send a stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit up to seven (2K) or fifteen (4K) more data words. The EEPROM will respond with a “0” after each data word received. The microcontroller must terminate the page write sequence with a stop condition, as shown in Figure 9.

Figure 9. Page Write



The data word address lower three (2K) or four (4K) bits are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than eight (2K) or sixteen (4K) data words are transmitted to the EEPROM, the data word address will “roll over” and previous data will be overwritten.

ACKNOWLEDGE POLLING: Once the internally-timed write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired. Only if the internal write cycle has completed will the EEPROM respond with a “0” allowing the read or write sequence to continue.

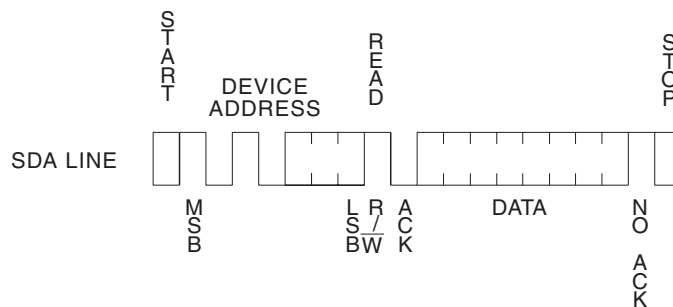
Read Operations

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to “1”. There are three read operations: current address read, random address read and sequential read.

CURRENT ADDRESS READ: The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address “roll over” during read is from the last byte of the last memory page to the first byte of the first page. The address “roll over” during write is from the last byte of the current page to the first byte of the same page.

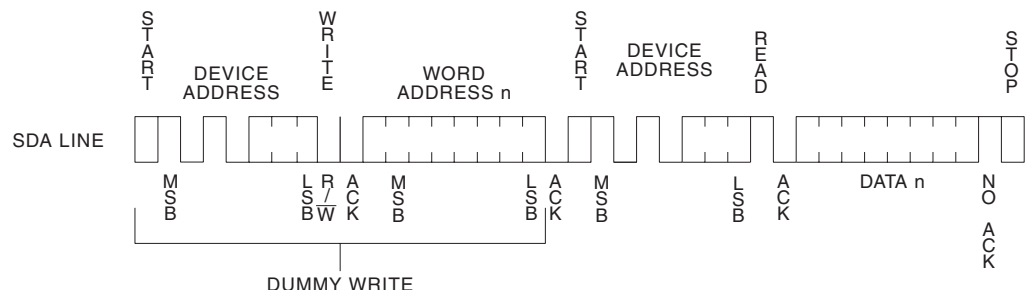
Once the device address with the read/write select bit set to “1” is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input “0” but does generate a following stop condition, as shown in Figure 10.

Figure 10. Current Address Read



RANDOM READ: A random read requires a “dummy” byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another start condition. The microcontroller now initiates a current address read by sending a device address with the read/write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a “0” but does generate a following stop condition, as shown in Figure 11.

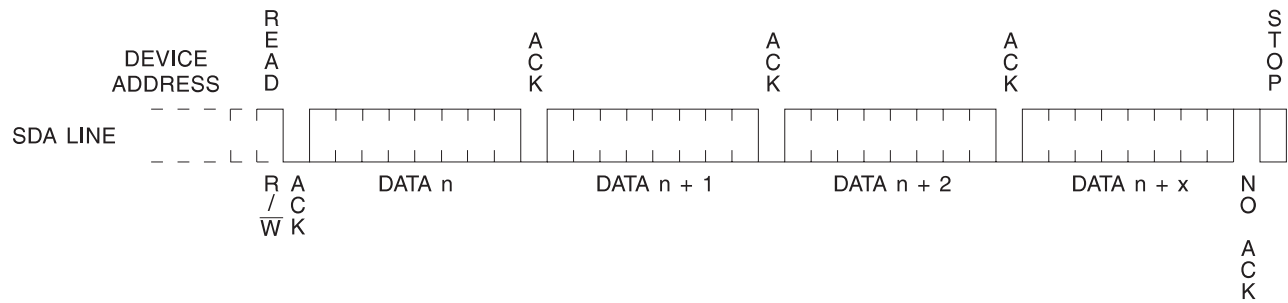
Figure 11. Random Read



SEQUENTIAL READ: Sequential reads are initiated by either a current address read or a random address read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will “roll over” and the sequential read will continue. The sequential read operation is terminated when the

microcontroller does not respond with a "0" but does generate a following stop condition, as shown in Figure 12.

Figure 12. Sequential Read



AT24C02A Ordering Information⁽¹⁾

| Ordering Code | Package | Operation Range |
|---|------------|---|
| AT24C02AN-10SQ-2.7 AT24C02A-10TQ-2.7 | 8S1 8A2 | Lead-free/Halogen-free/ Automotive Temperature (–40°C to 125°C) |

Note: 1. This device is not recommended for new design. Please refer to AT24HC02B Automotive datasheet.

| Package Type | |
|--------------|---|
| 8S1 | 8-lead, 0.150" Wide, Plastic Gull Wing Small Outline (JEDEC SOIC) |
| 8A2 | 8-lead, 0.170" Wide, Thin Shrink Small Outline Package (TSSOP) |
| Options | |
| –2.7 | Low Voltage (2.7V to 5.5V) |



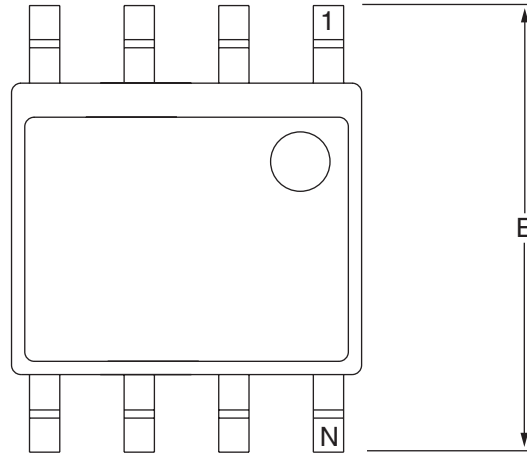
AT24C04A Ordering Information

| Ordering Code | Package | Operation Range |
|---|------------|--|
| AT24C04A-10TQ-2.7 AT24C04AN-10SQ-2.7 | 8A2 8S1 | Lead-free/Halogen-free Automotive Temperature (–40°C to 125°C) |

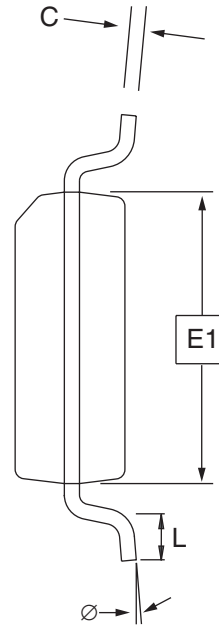
| Package Type | |
|--------------|---|
| 8S1 | 8-lead, 0.150" Wide, Plastic Gull Wing Small Outline (JEDEC SOIC) |
| 8A2 | 8-lead, 0.170" Wide, Thin Shrink Small Outline Package (TSSOP) |
| Options | |
| –2.7 | Low Voltage (2.7V to 5.5V) |

Packaging Information

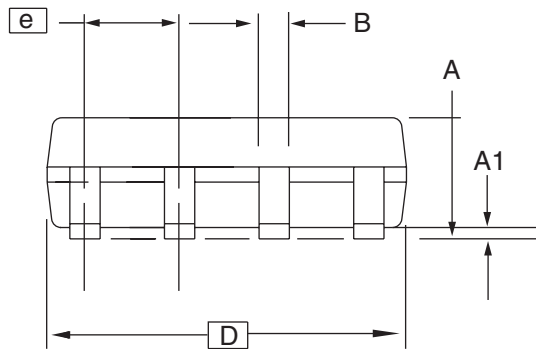
8S1 – JEDEC SOIC



Top View



End View



Side View

COMMON DIMENSIONS
(Unit of Measure = mm)

| SYMBOL | MIN | NOM | MAX | NOTE |
|--------|----------|-----|------|------|
| A | 1.35 | – | 1.75 | |
| A1 | 0.10 | – | 0.25 | |
| b | 0.31 | – | 0.51 | |
| C | 0.17 | – | 0.25 | |
| D | 4.80 | – | 5.00 | |
| E1 | 3.81 | – | 3.99 | |
| E | 5.79 | – | 6.20 | |
| e | 1.27 BSC | | | |
| L | 0.40 | – | 1.27 | |
| Ø | 0° | – | 8° | |

Note: These drawings are for general information only. Refer to JEDEC Drawing MS-012, Variation AA for proper dimensions, tolerances, datums, etc.

10/7/03



1150 E. Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906

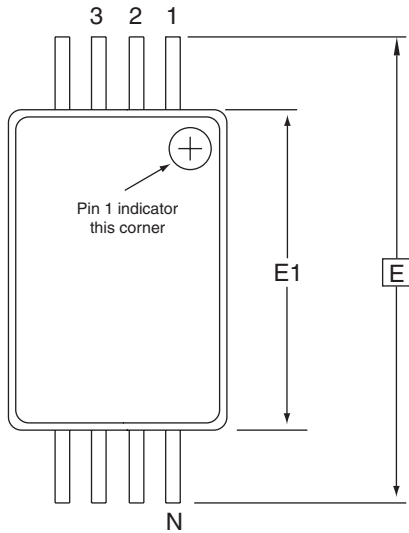
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8S1, 8-lead (0.150" Wide Body), Plastic Gull Wing
Small Outline (JEDEC SOIC)

DRAWING NO.
8S1

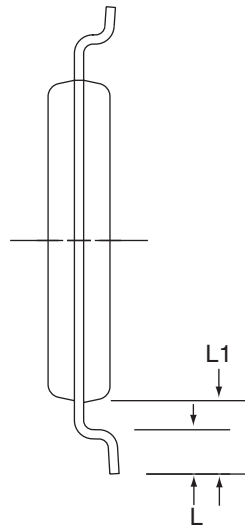
REV.
B



8A2 – TSSOP



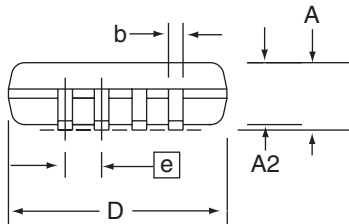
Top View



End View

COMMON DIMENSIONS (Unit of Measure = mm)

| SYMBOL | MIN | NOM | MAX | NOTE |
|--------|----------|------|------|------|
| D | 2.90 | 3.00 | 3.10 | 2, 5 |
| E | 6.40 BSC | | | |
| E1 | 4.30 | 4.40 | 4.50 | 3, 5 |
| A | – | – | 1.20 | |
| A2 | 0.80 | 1.00 | 1.05 | |
| b | 0.19 | – | 0.30 | 4 |
| e | 0.65 BSC | | | |
| L | 0.45 | 0.60 | 0.75 | |
| L1 | 1.00 REF | | | |



Side View

- Notes:
1. This drawing is for general information only. Refer to JEDEC Drawing MO-153, Variation AA, for proper dimensions, tolerances, datums, etc.
 2. Dimension D does not include mold Flash, protrusions or gate burrs. Mold Flash, protrusions and gate burrs shall not exceed 0.15 mm (0.006 in) per side.
 3. Dimension E1 does not include inter-lead Flash or protrusions. Inter-lead Flash and protrusions shall not exceed 0.25 mm (0.010 in) per side.
 4. Dimension b does not include Dambar protrusion. Allowable Dambar protrusion shall be 0.08 mm total in excess of the b dimension at maximum material condition. Dambar cannot be located on the lower radius of the foot. Minimum space between protrusion and adjacent lead is 0.07 mm.
 5. Dimension D and E1 to be determined at Datum Plane H.

5/30/02



2325 Orchard Parkway
San Jose, CA 95131

TITLE

8A2, 8-lead, 4.4 mm Body, Plastic
Thin Shrink Small Outline Package (TSSOP)

DRAWING NO.

8A2

REV.

B

Revision History

| Doc. Rev. | Date | Comments |
|-----------|--------|---|
| 5093D | 4/2007 | Added 'Not recommended for new design' note to page 1 and 11 for AT24C02A |
| 5093C | 1/2007 | Implemented revision history Remove PDIP package offering Remove PB'd parts |



Atmel Corporation

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 487-2600

Regional Headquarters

Europe

Atmel Sarl
Route des Arsenaux 41
Case Postale 80
CH-1705 Fribourg
Switzerland
Tel: (41) 26-426-5555
Fax: (41) 26-426-5500

Asia

Room 1219
Chinachem Golden Plaza
77 Mody Road Tsimshatsui
East Kowloon
Hong Kong
Tel: (852) 2721-9778
Fax: (852) 2722-1369

Japan

9F, Tonetsu Shinkawa Bldg.
1-24-8 Shinkawa
Chuo-ku, Tokyo 104-0033
Japan
Tel: (81) 3-3523-3551
Fax: (81) 3-3523-7581

Atmel Operations

Memory

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 436-4314

Microcontrollers

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 436-4314

La Chantrerie
BP 70602
44306 Nantes Cedex 3, France
Tel: (33) 2-40-18-18-18
Fax: (33) 2-40-18-19-60

ASIC/ASSP/Smart Cards

Zone Industrielle
13106 Rousset Cedex, France
Tel: (33) 4-42-53-60-00
Fax: (33) 4-42-53-60-01

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906, USA
Tel: 1(719) 576-3300
Fax: 1(719) 540-1759

Scottish Enterprise Technology Park
Maxwell Building
East Kilbride G75 0QR, Scotland
Tel: (44) 1355-803-000
Fax: (44) 1355-242-743

RF/Automotive

Theresienstrasse 2
Postfach 3535
74025 Heilbronn, Germany
Tel: (49) 71-31-67-0
Fax: (49) 71-31-67-2340

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906, USA
Tel: 1(719) 576-3300
Fax: 1(719) 540-1759

Biometrics/Imaging/Hi-Rel MPU/ High Speed Converters/RF Datacom

Avenue de Rochepleine
BP 123
38521 Saint-Egreve Cedex, France
Tel: (33) 4-76-58-30-00
Fax: (33) 4-76-58-34-80

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